Oriental motor

ORIENTAL MOTOR U.S.A. Corp. 570 Alaska Avenue Torrance, CA 90503 1-800-GO-VEXTA (468-3982)

Item # AZM66AC-TS3.6, 2.36 in. (60 mm) AZ Series Taper Hobbed Gear Stepper Motor with Mechanical Absolute Encoder (Gear Ratio: 3.6:1) (AC Input)



OSTEP Hybrid Step-Servo

The α STEP AZ Series stepper motor offers closed loop control, substantially reduces heat generation from the motor and by incorporating the newly developed Mechanical Absolute Encoder, absolute-type positioning is available, without battery back up or external sensors to buy.

• Requires αSTEP AZ Series Driver

*Connection Cables required (sold separately)

.**91**3 €

Specifications | Dimensions | Speed-Torque | Rotation | System | Product Number

Spe	pecifications -		
	Lead Time ¹	Up to 10 pcs as of 6:30am EST Estimated Ship: 01/15/2026	
	Frame Size	2.36 in	
	Motor Length	4.53 in.	
	Driver Voltage Input Power	AC	
	Speed-Torque Characteristics	Speed - Torque Characteristics Speed - Torque Characteristics	
	Holding Torque	255 oz-in	
	Holding Torque at Motor Standstill	184 oz-in	
	Туре	Mechanical Absolute Encoder	



Web Price - \$627.00

Shaft/Gear Type	Taper Hobbed Gear
Gear Ratio (X:1)	3.6 :1
Backlash	35 arc min (0.59°)
Shaft	Single
Electromagnetic Brake	Not Equipped
Connection Type	Cable
Resolution (Resolution Setting: 1000 P/R)	0.1 °/Pulse
Permissible Speed Range (r/min)	0 ~ 833
Rotor Inertia	2 oz-in²
Stop Position Accuracy	±3 arc minutes (±0.05°)
Shaft Runout	0.05 mm (0.002 in.) T.I.R.
Concentricity	0.075 mm (0.003 in.) T.I.R.
Permissible Overhung Load	0 in. from Shaft End = 27 lb 0.2 in. from Shaft End = 30 lb 0.39 in. from Shaft End = 33 lb 0.59 in. from Shaft End = 37 lb 0.79 in. from Shaft End = 40 lb
Permissible Thrust Load	8.9 lb
RoHS Compliant	These products do not contain substances that exceed the regulation values in the RoHS Directive.
Perpendicularity	0.075 mm (0.003 in.) T.I.R.
Safety Standards	UL CSA CE
CE Marking	Low Voltage Directives EMC Directives
California Proposition 65	⚠ CA WARNING Cancer risk from exposure to Nickel. See www.P65Warnings.ca.gov Risk of reproductive harm from exposure to Di-n-hexyl phthalate (DnHP). See www.P65Warnings.ca.gov Risk of cancer and reproductive harm from exposure to Di(2- ethylhexyl phthalate (DEHP). See www.P65Warnings.ca.gov See "?" or copy/paste www.P65Warnings.ca.gov in your browser.

Insulation Class	Class B [130°C (266°F)] [Recognized as 105 (A) by UL.]
Insulation Resistance	100 $\text{M}\Omega$ or more when 500 VDC megger is applied between the following places: Case - Motor and sensor windings
Dielectric Strength	Sufficient to withstand the following for 1 minute: Case - Motor and sensor windings 1.5 kVAC 50 Hz or 60 Hz
Ambient Temperature	0 ~ 40°C (32 ~ 104°F) (non-freezing)
Ambient Humidity	85% or less (Non-condensing)
Degree of Protection	IP66 (excluding the mounting surface and connector)

Dimensions

-

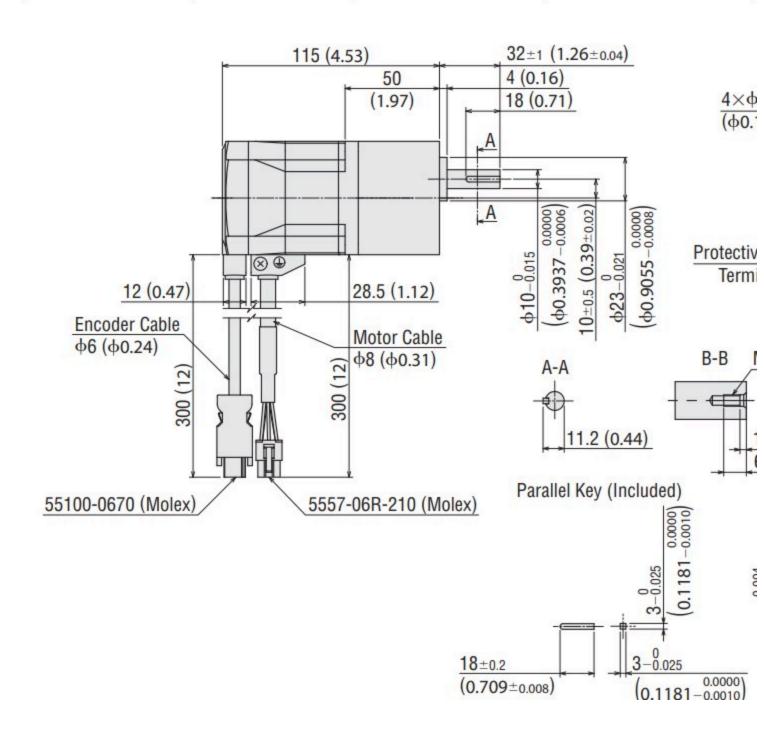
Dimensions Unit = mm (in.)

Motors

♦ TS Geared Type

Frame Size 60 mm (2.36 in.)

Product Name		Motor Product Name	Gear Ratio	
Built-In Controller	Pulse Input	Wold Floudt Name	ucai naliu	
AZ66A□D-TS□-♦	AZ66A TS-	AZM66AC-TS□	3.6, 7.2, 10, 20, 30	



Speed-Torque

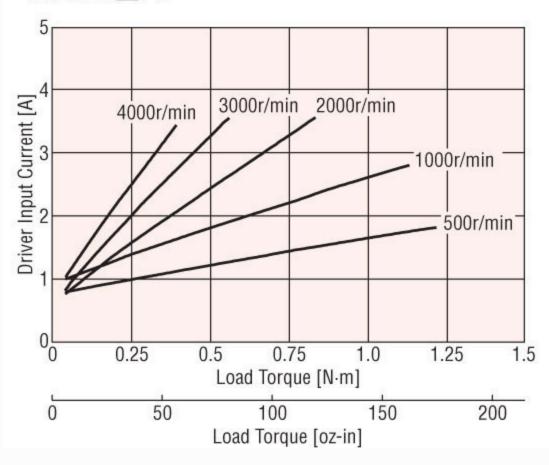
Load Torque - Driver Input Current Characte

This is the relationship between the load torque and driver input current at each speed when the material is actually operated. From these characteristics, the power supply capacity required for use in multiple operation can be estimated. For the geared type, convert to torque and speed by the motor shaft.

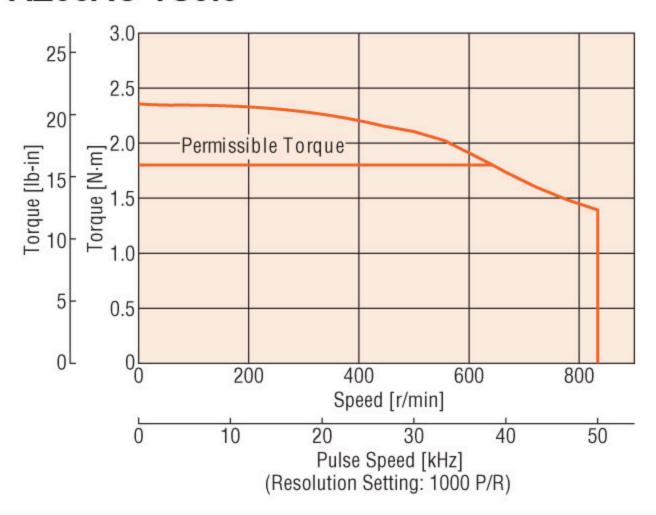
Motor Shaft Speed = Gear Output Shaft Speed x Gear Ratio [r/min]

Motor Shaft Torque = Gear Output Shaft Torque / Gear Ratio [N·m (oz-in)]

AZ66□A



■Speed – Torque Characteristics (Reference va AZ66AC-TS3.6



Rotation

Rotation Direction

Harmonic Geared

This indicates the rotation direction as viewed from the output shaft side of the motor (factory setting).

Opposite direction

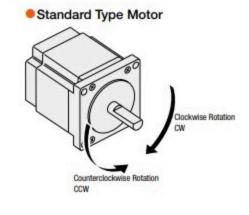
The rotation direction of the output gear shaft relative to the standard type motor output shaft varies depending on the gear type and gear ratio.

Please check the following table.

riease check the following table.			
Type	Gear Ratio	Rotation direction Relative to Motor Output Shaft	

Type	Gear Ratio	Motor Output Shaft
TS Geared	3.6, 7.2, 10	Same direction
15 Geared	20, 30	Opposite direction
SH Geared	7.2,36	Same direction
Frame Size 28 mm (1.10 in.)	9, 10, 18	Opposite direction
SH Geared	3.6, 7.2, 9, 10	Same direction
Frame Size 42 mm (1.62 in.), 60 mm (2.36 in.)	18, 36	Opposite direction
PS Geared	All gear ratios	Same direction
PLE Geared	All gear ratios	Opposite direction
FC Geared	All gear ratios	Same direction
CONTRACTOR	CONTRACTOR AND CONTRA	And the Control of th

All gear ratios



System

-

* Not

System Configuration

Pulse Input Type, Standard Type with Electromagnetic Brake

A single-axis system configuration with the SCX11 Series controller is shown below.

Accessories (Sold separately) When extending the distance between the motor and the When extending the distance between the motor and driver without using the included connection cable driver using the included connection cable For Motor For Motor MCS Couplings For Encoder For Encoder Electromagnetic Electromagnetic Brake Brake **Connection Cable Sets Extension Cable Sets** Flexible Connection Cable Sets Flexible Extension Cable Sets **Data Setting Software** MEXE02 24 VDC Power Supply for Control* AZ Series To USB Port Driver Motor Computer* For Electromagnetic Brake For Encoder Programmable Controller* For Motor Controller (Sold separately) Controller **AC Power Supply** (Main power supply) Accessories (Sold separately) 24 VDC Power Supply* **Motor Mounting Brackets General-Purpose Cables**

System Configuration

Motor Mounting Brackets

Built-in Controller Type, Standard Type with Electromagnetic Brake An example of a configuration using I/O control or RS-485 communication is shown below. * No Accessories (Sold separately) When extending the distance between the motor and driver When extending the distance between the motor and the without using the included connection cable driver using the included connection cable MCS Couplings For Motor For Motor For Encoder Electromagnetic Electromagnetic Brake Brake **Connection Cable Sets Extension Cable Sets** Flexible Extension Cable Sets Flexible Connection Cable Sets 24 VDC Power Supply for Control* **AZ** Series **Data Setting Software** MEXE02 Driver Motor For Electromagnetic Brake To USB Port For Encoder Computer* For Motor (For RS-485 communication) Programmable Controller* **AC Power Supply** (Main power supply) Accessories (Sold separately) Peripheral Products (Sold separately)

General-Purpose Cables

Network Converters

Product Number

RS-485 Communication Cables

Product Number Code

Motor

AZM 66AC

(1) (2) (3) (4) (5)

◇PS, HPG, Harmonic Geared Type

AZM 6 6 A C - HP 15 F

① 23456

TS Geared Type

AZM 6 6 A C - TS 7.2 U

0 2 3 4 5 6 7 8

FC Geared Type

AZM 6 6 A C - FC 7.2 U A

0 2 3 4 5 6 7 8

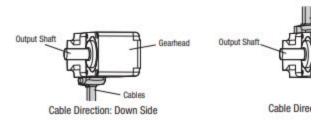
	_	_	

1	Motor Type	AZM: AZ Series Motor
	Motor Frame Size	4: 42 mm (1.65 in.) (HPG
(3)		(1.57 in.))
2		6: 60 mm (2.36 in.)
		9: 85 mm (3.35 in.) (Geared
3	Motor Case Length	
4	Output Shaft Configuration	A: Single Shaft M: Electro
(5)	Motor Specifications	C: AC Power Supply Input S
	Gear Type	PS: PS Geared Type
6	50.00	HP: HPG Geared Type
		HS: Harmonic Geared Type
7	Gear Ratio	
_	Output Shaft Type	HPG Geared Type
8		Blank: Shaft Output F: Fla

1	Motor Type	AZM: AZ Series Motor
	Motor Frame Size	4: 42 mm (1.65 in.)
2		6: 60 mm (2.36 in.)
		9: 90 mm (3.54 in.)
3	Motor Case Length	
4	Output Shaft Type	A: Single Shaft M: Electro
(5)	Motor Type	C: AC Power Supply Input S
6	Geared Type	TS: TS Geared Type
7	Gear Ratio	
8	Cable Outlet Direction	U: Upper Side L: Left Side

1	Motor Type	AZM: AZ Series Motor
2	Motor Frame Size	4: 42 mm (1.65 in.) 6: 60
3	Motor Case Length	
4	Output Shaft Type	A: Single Shaft M: Electro
(5)	Motor Type	C: AC Power Supply Input S
6	Geared Type	FC: FC Geared Type
7	Gear Ratio	
8	Cable Outlet Direction*	D: Down Side U: Upper S
9	Identification Symbol	A: Solid Shaft

*The cable direction is when viewed from the gearhead side with the out



1		CC: Cable
2	Length	010: 1 m (3.3 ft.) 020: 2 m (6.6 ft.) 030: 3 m (9.8 ft.) 050: 5 m (16.4 ft.) 070: 7 m (23 ft.) 100: 10 m (32.8 ft.) 200: 20 m (6:
3	Reference Number	
4	Applicable Product	Z: AZ Series

Connection Cable Set / Flexible Connection Cable Set

CC 050 V Z F B

2 3 4 5 6

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(5)	Cable Type	F: Connection Cable Set R: Flexible Connection Cable Set
6	Description	Blank: Without Electromagnetic Brake B: With Electromagnetic Brake

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¹ Quoted Ship Date for orders placed before 12:00 pm PST. Quantities may affect Shipping Date.